

1. Let \mathbb{F} be the set of all 2×2 matrices of the form $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$, where a and b are real numbers. With the usual matrix addition and multiplication, is \mathbb{F} a field? Explain.

\mathbb{F} is a field. We get most of the axioms for free, from the defn. of addition & multiplication, but we need to check that mult. commutes ~~and~~ that we have inverses & closure under mult.

$$\begin{bmatrix} a & -b \\ b & a \end{bmatrix} \begin{bmatrix} c & -d \\ d & c \end{bmatrix} = \begin{bmatrix} ac-bd & -bc-ad \\ bc+ad & ac-bd \end{bmatrix} = \begin{bmatrix} c & -d \\ d & c \end{bmatrix} \begin{bmatrix} a & -b \\ b & a \end{bmatrix} \in \mathbb{F}$$

$$\text{Inverses: } \begin{bmatrix} a & -b \\ b & a \end{bmatrix}^{-1} = \frac{1}{a^2+b^2} \begin{bmatrix} a & b \\ -b & a \end{bmatrix} \in \mathbb{F}$$

2. Let $\{\vec{v}_1, \dots, \vec{v}_n\}$ be an orthonormal set of vectors. Show that they are linearly independent.

$$\text{Say } c_1 \vec{v}_1 + \dots + c_n \vec{v}_n = \vec{0}.$$

Dot both sides with \vec{v}_i :

$$\vec{v}_i \cdot (c_1 \vec{v}_1 + \dots + c_n \vec{v}_n) = \vec{v}_i \cdot \vec{0}$$

$$\Leftrightarrow c_1 (\vec{v}_i \cdot \vec{v}_1) + \dots + c_n (\vec{v}_i \cdot \vec{v}_n) = 0$$

$$c_i = 0 \quad (\text{since } \vec{v}_j \cdot \vec{v}_k = 0 \text{ if } j \neq k \\ 1 \text{ if } j=k)$$

So all the c_i 's are 0, so $\{\vec{v}_1, \dots, \vec{v}_n\}$ are lin. ind.

3. Find the equation $y = mx + b$ of the line that best fits the data points $(0, 1)$, $(3, 4)$, and $(6, 5)$.

"Solve" $m \cdot 0 + b = 1$
 $m \cdot 3 + b = 4$, or $\begin{bmatrix} 0 & 1 \\ 3 & 1 \\ 6 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \\ 5 \end{bmatrix}$
 $m \cdot 6 + b = 5$

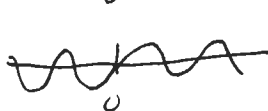
Least squares: $\begin{bmatrix} 0 & 3 & 6 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 3 & 1 \\ 6 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 0 & 3 & 6 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \\ 5 \end{bmatrix}$
 $\begin{bmatrix} 45 & 9 \\ 9 & 3 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 42 \\ 10 \end{bmatrix}$

Row reduce $\begin{bmatrix} 45 & 9 & 42 \\ 9 & 3 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1/5 & 14/15 \\ 9 & 3 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1/5 & 14/15 \\ 0 & 6/5 & 8/5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1/5 & 14/15 \\ 0 & 1 & 4/3 \end{bmatrix}$
 $\rightarrow \begin{bmatrix} 1 & 0 & 2/3 \\ 0 & 1 & 4/3 \end{bmatrix} \quad m = 2/3, b = 4/3, \text{ or } y = 2/3 x + 4/3$

4. Let $C[-\pi, \pi]$ be the space of all continuous functions $f: [-\pi, \pi] \rightarrow \mathbb{R}$. Let V be the subspace of $C[-\pi, \pi]$ spanned by the set of functions $\{\sin(t), \sin(2t), \sin(3t), \dots\}$. Show that the function $f(x) = |x|$ is an element of V^\perp . (We are using the usual inner product on $C[-\pi, \pi]$.)

$$\langle f, g \rangle = \int_{-\pi}^{\pi} fg \, dx$$

$f(x) = |x|$ is even 

& $\sin(kx)$ is odd 

So $f(x)\sin(kx)$ is odd. The integral of an odd function over a symmetric interval is 0 (cancellation), so $\langle f, \sin(kx) \rangle = 0$ for every k . Thus $f \in V^\perp$.

5. Let A and B be two 3×3 matrices such that $\det A = 7$ and $\det B = 2$. Compute the following, or prove that you don't have enough information:

(a) $\det A^T$

$$= \det A = 7$$

(b) $\det A^{-1} = \frac{1}{\det A} = \frac{1}{7}$

(c) $\det A + B$ Not enough info. For example, if $A = \begin{bmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ & $B = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$,
then $\det A + B = 9$

But if $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, then $\det A + B = 24$

(d) $\det AB$

$$= (\det A)(\det B) = 14$$

(e) $\det 5A = 5^3 \det A$ (pull a 5 out of each row)
 $= 125 \det A$

(f) $\det A_{\text{diag}}$ (A_{diag} is the matrix whose diagonal entries are identical to those of A , and whose off-diagonal entries are 0).

Not enough info. If $A = \begin{bmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, then $\det A_{\text{diag}} = 7$.

But if $A = \begin{bmatrix} 7 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$, then $\det A_{\text{diag}} = 0$.

6. Let V be the span in \mathbb{R}^3 of the vectors $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \right\}$.

(a) Find a basis for V^\perp .

$$\vec{x} \in V^\perp \iff \vec{x} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \vec{x} \cdot \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} = 0, \text{ i.e., } \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \text{ satisfies}$$

$$\begin{aligned} x_1 + x_2 + x_3 &= 0 \\ 2x_1 + 3x_2 + 4x_3 &= 0 \end{aligned} \quad \text{row reduce } \begin{bmatrix} 1 & 1 & 1 \\ 2 & 3 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \end{bmatrix}$$

$$\text{So } x_1 = x_3 \text{ \& } x_2 = -2x_3, \text{ or } \vec{x} = x_3 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

$$\text{So the basis is } \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \right\}$$

(b) Find the matrix M_T for the transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $T(\vec{x}) = \text{proj}_{V^\perp} \vec{x}$. (If you didn't get part (a), use the basis $B = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$, which is obviously not the right answer.)

The matrix for projection onto a unit vector \vec{u} is $\vec{u} \vec{u}^T$.

$\vec{u} = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$ is a unit vector that spans V^\perp , so

$$M_T = \left(\frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \right) \left(\frac{1}{\sqrt{6}} [1 \ -2 \ 1] \right) = \frac{1}{6} \begin{bmatrix} 1 & -2 & 1 \\ -2 & 4 & -2 \\ 1 & -2 & 1 \end{bmatrix}$$

(If you used $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ you should get $\frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$.)

(c) Use part (b) to find the matrix M_S for the transformation $S: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $S(\vec{x}) = \text{proj}_V \vec{x}$. (If you didn't get (b), use the matrix $M_T = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix}$.)

Observe that $\vec{x} = \text{proj}_V \vec{x} + \text{proj}_{V^\perp} \vec{x}$, or $\text{proj}_V \vec{x} = \vec{x} - \text{proj}_{V^\perp} \vec{x}$,

$$\text{So } M_S = \text{Id} - M_T = \begin{bmatrix} \frac{5}{6} & \frac{1}{3} & -\frac{1}{6} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ -\frac{1}{6} & \frac{1}{3} & \frac{5}{6} \end{bmatrix}$$

7. Compute the determinant of $\begin{bmatrix} 2 & -8 & 6 & 8 \\ 3 & -9 & 5 & 10 \\ -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 \end{bmatrix}$.

$$\det = 2 \det \begin{bmatrix} 1 & -4 & 3 & 4 \\ 3 & -9 & 5 & 10 \\ -3 & 0 & 1 & -2 \\ 1 & -4 & 0 & 6 \end{bmatrix} = 2 \det \begin{bmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & -12 & 10 & 10 \\ 0 & 0 & -3 & 2 \end{bmatrix}$$

$$= 2 \det \begin{bmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & 0 & -6 & 2 \\ 0 & 0 & -3 & 2 \end{bmatrix} = 2 \det \begin{bmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & 0 & -6 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= 2 \cdot 3 \cdot -6 = -36$$

(EXTRA CREDIT) (5 pts) Let \vec{x} and \vec{y} be two vectors in a (real) inner product space. Find $\langle \vec{x}, \vec{y} \rangle$, given that $\|\vec{x} + \vec{y}\| = 2$ and $\|\vec{x} - \vec{y}\| = 3$.

Observe: ~~$\langle \vec{x}, \vec{y} \rangle = \langle \vec{x}, \vec{x} \rangle$~~

$$\|\vec{x} + \vec{y}\|^2 = \langle \vec{x} + \vec{y}, \vec{x} + \vec{y} \rangle = \langle \vec{x}, \vec{x} \rangle + 2\langle \vec{x}, \vec{y} \rangle + \langle \vec{y}, \vec{y} \rangle$$

$$\|\vec{x} - \vec{y}\|^2 = \langle \vec{x} - \vec{y}, \vec{x} - \vec{y} \rangle = \langle \vec{x}, \vec{x} \rangle - 2\langle \vec{x}, \vec{y} \rangle + \langle \vec{y}, \vec{y} \rangle$$

$$\text{So } \|\vec{x} + \vec{y}\|^2 - \|\vec{x} - \vec{y}\|^2 = 4\langle \vec{x}, \vec{y} \rangle.$$

$$\text{So } \langle \vec{x}, \vec{y} \rangle = \frac{1}{4}(4 - 9) = -\frac{5}{4}$$