

## Calculations for IFS for flowsnake

$$deg := \frac{\text{Pi}}{180} \qquad \frac{1}{180} \pi \qquad (1)$$

$$A := \frac{\arcsin\left(\frac{\text{sqrt}(3)}{2 \cdot \text{sqrt}(7)}\right) \cdot 180}{\text{Pi}} \qquad \frac{180 \arcsin\left(\frac{1}{14} \sqrt{3} \sqrt{7}\right)}{\pi} \qquad (2)$$

$$\text{evalf}(A) \qquad 19.10660535 \qquad (3)$$

$$r := \frac{1}{\text{sqrt}(7)} \qquad \frac{1}{7} \sqrt{7} \qquad (4)$$

### Rotation matrix in degrees, with scaling by r

$$\text{rot} := x \rightarrow \begin{bmatrix} \text{expand}(r \cdot \cos(x \cdot \text{deg})) & \text{expand}(-r \cdot \sin(x \cdot \text{deg})) \\ \text{expand}(r \cdot \sin(x \cdot \text{deg})) & \text{expand}(r \cdot \cos(x \cdot \text{deg})) \end{bmatrix} :$$

### Matrix for segments 1 and 4

$$M1 := \text{rot}(A - 120) \qquad \begin{bmatrix} -\frac{1}{14} & \frac{3}{14} \sqrt{3} \\ -\frac{3}{14} \sqrt{3} & -\frac{1}{14} \end{bmatrix} \qquad (5)$$

### Matrix for segments 2, 3, 5, and 7

$$M2 := \text{rot}(A) \qquad \begin{bmatrix} \frac{5}{14} & -\frac{1}{14} \sqrt{3} \\ \frac{1}{14} \sqrt{3} & \frac{5}{14} \end{bmatrix} \qquad (6)$$

### Matrix for segment 6

$$M3 := \text{rot}(120 + A)$$

$$\begin{bmatrix} -\frac{2}{7} & -\frac{1}{7}\sqrt{3} \\ \frac{1}{7}\sqrt{3} & -\frac{2}{7} \end{bmatrix} \quad (7)$$

**Points needed for translations**

$$P1 := \text{expand}([r \cdot \cos((60 + A) \cdot \text{deg}), r \cdot \sin((60 + A) \cdot \text{deg})])$$

$$\left[ \frac{1}{14}, \frac{3}{14}\sqrt{3} \right] \quad (8)$$

$$P2 := P1 + \text{expand}([r \cdot \cos(A \cdot \text{deg}), r \cdot \sin(A \cdot \text{deg})])$$

$$\left[ \frac{3}{7}, \frac{2}{7}\sqrt{3} \right] \quad (9)$$

$$P3 := P2 + \text{expand}([r \cdot \cos(A \cdot \text{deg}), r \cdot \sin(A \cdot \text{deg})])$$

$$\left[ \frac{11}{14}, \frac{5}{14}\sqrt{3} \right] \quad (10)$$

$$P4 := \text{expand}([r \cdot \cos(A \cdot \text{deg}), r \cdot \sin(A \cdot \text{deg})])$$

$$\left[ \frac{5}{14}, \frac{1}{14}\sqrt{3} \right] \quad (11)$$

$$P5 := \text{expand}([1 - r \cdot \cos(A \cdot \text{deg}), -r \cdot \sin(A \cdot \text{deg})])$$

$$\left[ \frac{9}{14}, -\frac{1}{14}\sqrt{3} \right] \quad (12)$$

**Decimal values for matrices and translation vectors**

$$\text{evalf}(M1)$$

$$\begin{bmatrix} -0.07142857143 & 0.3711537446 \\ -0.3711537446 & -0.07142857143 \end{bmatrix} \quad (13)$$

$$\text{evalf}(M2)$$

$$\begin{bmatrix} 0.3571428571 & -0.1237179149 \\ 0.1237179149 & 0.3571428571 \end{bmatrix} \quad (14)$$

$$\text{evalf}(M3)$$

$$\begin{bmatrix} -0.2857142857 & -0.2474358298 \\ 0.2474358298 & -0.2857142857 \end{bmatrix} \quad (15)$$

$$\text{evalf}(P1)$$

$$[0.07142857143, 0.3711537446] \quad (16)$$

$$\text{evalf}(P2)$$

$$[0.4285714286, 0.4948716594] \quad (17)$$

$$\text{evalf}(P3)$$

$$[0.7857142857, 0.6185895742] \quad (18)$$

$$\text{evalf}(P4)$$

$$[0.3571428571, 0.1237179149] \quad (19)$$

*evalf*(P5)

[0.6428571429, -0.1237179149]

(20)

**Verify the trig values for the rotation angles**

*expand*( $\sin(A \cdot \text{deg})$ )

$$\frac{1}{14} \sqrt{3} \sqrt{7} \quad (21)$$

*expand*( $\cos(A \cdot \text{deg})$ )

$$\frac{5}{14} \sqrt{7} \quad (22)$$

*expand*( $\sin((A - 120) \cdot \text{deg})$ )

$$-\frac{3}{14} \sqrt{3} \sqrt{7} \quad (23)$$

*expand*( $\cos((A - 120) \cdot \text{deg})$ )

$$-\frac{1}{14} \sqrt{7} \quad (24)$$

*expand*( $\sin((A + 120) \cdot \text{deg})$ )

$$\frac{1}{7} \sqrt{3} \sqrt{7} \quad (25)$$

*expand*( $\cos((A + 120) \cdot \text{deg})$ )

$$-\frac{2}{7} \sqrt{7} \quad (26)$$